Refereed Journal Publications:

R. Goebel, A. Teel, T. Hu, and Z. Lin, *Conjugate convex Lyapunov functions for dual linear differential inclusions*, to appear in IEEE Transactions on Automatic Control.

R. Goebel, *Stabilizing a linear system with saturation through optimal control*, to appear in IEEE Transactions on Automatic Control.

R. Goebel, *Duality and uniqueness of convex solutions to stationary Hamilton-Jacobi equations*, Transactions of the AMS, Volume 357, 2005, 2165-2186.

R.Goebel, *Convex optimal control problems with smooth Hamiltonians*, SIAM Journal of Control and Optimization, Volume 43, Number 5, 2005, 1787-1811.

J. Borwein and R. Goebel, *On the nondifferentiability of cone-monotone functions in Banach spaces*, to appear in Optimization: Structure and Applications, E. Hunt and C.E.M. Pearce editors, Applied Optimization Series, Kluwer Academic Publishers.

R. Goebel, *Regularity of the optimal feedback and the value function in convex problems of optimal control*, Set-Valued Analysis, Volume 12, Issue 1-2, 2004, 127-145.

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R. Goebel, *Planar generalized Hamiltonian systems with large saddle sets*, Journal of Nonlinear and Convex Analysis, Volume 3, Number 3, 2002, 365-380.

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R. Goebel, *Sufficient condition for stability of an L^2-angle*, Bulletin of the Polish Academy of Science, Vol 45, No 3, 1997, 227–232.

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R. Goebel and M. Subbotin, *Continuous Time Constrained Linear Quadratic Regulator – Convex Duality Approach*, submitted March 2005.

T. Hu, A. Teel, R. Goebel, and Z. Lin, *Conjugate Lyapunov functions for saturated linear systems*, submitted November 2004.

R. Goebel and A. Teel, *Solutions to hybrid inclusions via set and graphical convergence with stability theory applications*, submitted August 2004.

Refereed Conference Proceedings Contributions:

R. Goebel and M. Subbotin, *Continuous time constrained Linear Quadratic Regulator – convex duality approach*, to appear in Proceedings of the American Control Conference 2005.

R. Sanfelice, R. Goebel, and A. Teel, *Results on convergence in hybrid systems via detectability and an invariance principle*, to appear in Proceedings of the American Control Conference 2005.

C. Cai, A. Teel, and R. Goebel, Converse Lyapunov theorems and robust asymptotic stability for hybrid systems, to appear in the Proceedings of the American Control Conference 2005.

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T. Hu, Z. Lin, R. Goebel, and A. Teel, *Stability regions for saturated linear systems via conjugate Lyapnov functions*, Proceedings of the 43nd IEEE Conference on Decision and Control, 2004.

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